

GENERALIZED REIDEMEISTER NUMBER ON A TRANSFORMATION GROUP

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ABSTRACT. In this paper we study the generalized Reidemeister number $R(\varphi, \psi)$ for a self-map $(\varphi, \psi) : (X, G) \rightarrow (X, G)$ of a transformation group (X, G) , as an extension of the Reidemeister number $R(f)$ for a self-map $f : X \rightarrow X$ of a topological space X .

1. Introduction

It is observed that the number of the fixed point classes for a self-map $f : X \rightarrow X$ of a compact connected ANR could be calculated by defining an equivalence relation on the fundamental group $\pi_1(X, x_0)$.

The number of equivalence classes of $\pi_1(X, x_0)$, the Reidemeister number $R(f)$, equals the number of the fixed point classes of f .

F.Rhodes [3] represented the fundamental group $\sigma(X, x_0, G)$ of a transformation group (X, G) , a group G of homeomorphisms of a space X , as a generalization of the fundamental group $\pi_1(X, x_0)$ of a topological space X .

In the present paper we defined the generalized Reidemeister number $R(\varphi, \psi)$ for a self-map $(\varphi, \psi) : (X, G) \rightarrow (X, G)$ of the transformation group (X, G) and investigate its homotopy invariance. We also give the algebraic estimation of the definition of $R(\varphi, \psi)$ in the same way as in [2].

2. Preliminaries

Received November 15, 1996.

1991 Mathematics Subject Classification: Primary 55M20, 57M05.

Key words and phrases: $(\varphi, \psi)_\sigma$ -equivalent, (algebraic) Reidemeister number, diagonal path..

In this paper, a transformation group is a pair (X, G) , where X is a path connected space with base point x_0 and G is a group of homeomorphisms of X . A map $(\varphi, \psi): (X, G) \rightarrow (X, G)$ consists of a continuous map $\varphi: X \rightarrow X$ and a homomorphism $\psi: G \rightarrow G$ such that $\varphi(gx) = \psi(g)\varphi(x)$ for every pair (x, g) .

Given any element g of G , a path α of order g with base point x_0 is a continuous map $\alpha: I \rightarrow X$ such that $\alpha(0) = x_0$ and $\alpha(1) = gx_0$. A path α of order g_1 and a path β of order g_2 form a new path $\alpha + g_1\beta$ of order g_1g_2 defined by the following equations

$$(\alpha + g_1\beta)(t) = \begin{cases} \alpha(2t), & 0 \leq t \leq \frac{1}{2}, \\ g_1\beta(2t - 1), & \frac{1}{2} \leq t \leq 1. \end{cases}$$

Two paths α and β of the same order g are said to be homotopic if there is a continuous map $F: I \times I \rightarrow X$ such that

$$\begin{aligned} F(t, 0) &= \alpha(t), & 0 \leq t \leq 1, \\ F(t, 1) &= \beta(t), & 0 \leq t \leq 1, \\ F(0, s) &= x_0, & 0 \leq s \leq 1, \\ F(1, s) &= gx_0, & 0 \leq s \leq 1. \end{aligned}$$

The equivalence relation $\alpha \sim \beta$ denotes that α and β are homotopic paths of the same order. Denote the equivalence class containing a path α of order g by $[\alpha; g]$. Two homotopic classes of paths of different orders g_1 and g_2 are distinct, even if $g_1x_0 = g_2x_0$. F.Rhodes [3] showed that the set of homotopy classes of paths of prescribed order with the rule of composition $*$ is a group, where $*$ is defined by $[\alpha; g_1] * [\beta; g_2] = [\alpha + g_1\beta; g_1g_2]$. This group was called the fundamental group of (X, G) with base points x_0 , and was denoted by $\sigma(X, x_0, G)$. He also proved that $\sigma(X, x_0, G)$ is an invariant of the base point x_0 .

3. Main results

Let $(\varphi, \psi): (X, G) \rightarrow (X, G)$ be a mapping. It is easy to see that if α is a path in X of order g with base point x_0 then $\varphi\alpha$ is a path in X of order $\psi(g)$ with base point $\varphi(x_0)$. Furthermore, if $\alpha \sim \beta$ then $\varphi\alpha \sim \varphi\beta$. Thus (φ, ψ) induces a homomorphism $(\varphi, \psi)_*: \sigma(X, x_0, G) \rightarrow \sigma(X, \varphi(x_0), G)$ defined by $(\varphi, \psi)_*[\alpha; g] = [\varphi\alpha; \psi(g)]$.

If λ is a path from $\varphi(x_0)$ to x_0 , then λ induces an isomorphism

$$\lambda_* : \sigma(X, \varphi(x_0), G) \rightarrow \sigma(X, x_0, G)$$

defined by $\lambda_*[\alpha; g] = [\lambda\rho + \alpha + g\lambda; g]$ for each $[\alpha; g] \in \sigma(X, \varphi(x_0), G)$, where $\rho(t) = 1-t$. This isomorphism λ_* depends only on the homotopy class of λ .

Consider the composition

$$\sigma(X, x_0, G) \xrightarrow{(\varphi, \psi)_*} \sigma(X, \varphi(x_0), G) \xrightarrow{\lambda_*} \sigma(X, x_0, G).$$

DEFINITION 3.1. Let $\lambda_*(\varphi, \psi)_* = (\varphi, \psi)_\sigma$. Two elements $[\alpha; g_1]$ and $[\beta; g_2]$ in $\sigma(X, x_0, G)$ are said to be $(\varphi, \psi)_\sigma$ -equivalent, denoted by $[\alpha; g_1] \stackrel{(\varphi, \psi)_\sigma}{\sim} [\beta; g_2]$, if there exists $[\gamma; g] \in \sigma(X, x_0, G)$ such that $[\alpha; g_1] = [\gamma; g][\beta; g_2](\varphi, \psi)_\sigma([\gamma; g]^{-1})$. This is an equivalence relation on $\sigma(X, x_0, G)$. Let $\sigma(X, x_0, G)'(\varphi, \psi)_\sigma$ be the set of equivalence classes of $\sigma(X, x_0, G)$ under $(\varphi, \psi)_\sigma$ -equivalence.

The cardinality of $\sigma(X, x_0, G)'(\varphi, \psi)_\sigma$ is the *algebraic Reidemeister number* of $(\varphi, \psi)_\sigma$, and is denoted by $R_*(\varphi, \psi)_\sigma$. With this view, we may define the *Reidemeister number* of a map $(\varphi, \psi); (X, G) \rightarrow (X, G)$, $R(\varphi, \psi)$, to be the algebraic Reidemeister number of $(\varphi, \psi)_\sigma$. In symbols,

$$R(\varphi, \psi) = R_*(\varphi, \psi)_\sigma = \#\sigma(X, x_0, G)'(\varphi, \psi)_\sigma.$$

LEMMA 3.2. *The definition of $R(\varphi, \psi)$ is independent of the choice of the path λ from $\varphi(x_0)$ to x_0 .*

Proof. Let τ denote another path from $\varphi(x_0)$ to x_0 . Then $\lambda^{-1}\tau$ is a loop at x_0 and therefore induces an inner automorphism

$$(\lambda^{-1}\tau)_* : \sigma(X, x_0, G) \rightarrow \sigma(X, x_0, G)$$

generated by the element $[\lambda^{-1}\tau; e]$, since

$$(\lambda^{-1}\tau)_*[\alpha; g] = [\lambda^{-1}\tau\rho; e][\alpha; g][\lambda^{-1}\tau; e].$$

Applying this automorphism to the left-hand side of $\lambda_*(\varphi, \psi)_*$ we have

$$R_*(\lambda_*(\varphi, \psi)_*) = R_*(\tau_*\lambda_*^{-1}\lambda_*(\varphi, \psi)_*) = R_*(\tau_*(\varphi, \psi)_*).$$

Hence we have independence of the path λ . \square \square

For a given homotopy $F : \varphi_1 \cong \varphi_2 : X \rightarrow X$ and a given path $c : I \rightarrow X$, define the (diagonal) path $\langle F, c \rangle : I \rightarrow X$ by $\langle F, c \rangle(t) = F(c(t), t)$, $0 \leq t \leq 1$. Then the path $\langle F, c \rangle$ preserves inverse in the following sense.

LEMMA 3.3. [1] $\langle F, c \rangle^{-1} = \langle F^{-1}, c^{-1} \rangle$.

Our first result is the following.

THEOREM 3.4. (Homotopy Invariance) *Let $(\varphi_1, \psi_1), (\varphi_2, \psi_2)$ be self-maps of (X, G) . If $F : \varphi_1 \cong \varphi_2 : X \rightarrow X$ is homotopy from φ_1 to φ_2 , then $R(\varphi_1, \psi_1) = R(\varphi_2, \psi_2)$.*

Proof. Let $x_0 \in X$. Then $\langle F, x_0 \rangle$ is a path from $\varphi_1(x_0)$ to $\varphi_2(x_0)$. Thus the path $\langle F, x_0 \rangle$ induces a homomorphism

$$\langle F, x_0 \rangle_* : \sigma(X, \varphi_1(x_0), G) \rightarrow \sigma(X, \varphi_2(x_0), G).$$

So we obtain the following induced commutative diagram

$$\begin{array}{ccc} \sigma(X, x_0, G) & \xrightarrow{(\varphi_1, \psi_1)_*} & \sigma(X, \varphi_1(x_0), G) \\ (\varphi_2, \psi_2)_* \searrow & & \nearrow \langle F^{-1}, x_0 \rangle_* \\ & & \sigma(X, \varphi_2(x_0), G) \end{array}$$

From Lemma 3.2 and Lemma 3.3, we have

$$\begin{aligned} R(\varphi_1, \psi_1) &= R_*(\lambda_*(\varphi_1, \psi_1)_*) \\ &= R_*(\lambda_* \langle F, x_0 \rangle_*^{-1} (\varphi_2, \psi_2)_*) \\ &= R_*((\langle F^{-1}, x_0 \rangle \lambda)_*(\varphi_2, \psi_2)_*) \\ &= R(\varphi_2, \psi_2). \end{aligned}$$

Hence we complete the proof of theorem. \square \square

Let $\sigma(X, x_0, G)'$ be a commutator subgroup of $\sigma(X, x_0, G)$ generated by the set

$$\{[\alpha; g_1][\beta; g_2][\alpha; g_1]^{-1}[\beta; g_2]^{-1} \mid [\alpha; g_1][\beta; g_2] \in \sigma(X, x_0, G)\}.$$

For a convenient notation, we shall write $\bar{\sigma}(X, x_0, G)$ for the quotient group $\sigma(X, x_0, G)/\sigma(X, x_0, G)'$.

THEOREM 3.5. *If $(\varphi, \psi) : (X, G) \rightarrow (X, G)$ is a self-map, then*

$$R(\varphi, \psi) \geq \# \text{Coker}(1 - (\varphi, \psi))_{\bar{\sigma}} \geq 1,$$

where 1 and $(\varphi, \psi)_{\bar{\sigma}}$ denote respectively the identity isomorphism and the endomorphism of $\bar{\sigma}(X, x_0, G)$ induced by (φ, ψ) .

Proof. Obviously, there exists a canonical homomorphism

$$\theta_{\sigma} : \sigma(X, x_0, G) \rightarrow \bar{\sigma}(X, x_0, G)$$

such that $\text{Ker}\theta_{\sigma} = \sigma(X, x_0, G)'$. Hence the following diagram is commutative:

$$\begin{array}{ccc} \sigma(X, x_0, G) & \xrightarrow{(\varphi, \psi)_{\sigma}} & \sigma(X, x_0, G) \\ \downarrow \theta_{\sigma} & & \downarrow \theta_{\sigma} \\ \bar{\sigma}(X, x_0, G) & \xrightarrow{(\varphi, \psi)_{\bar{\sigma}}} & \bar{\sigma}(X, x_0, G) \end{array}$$

For $[\gamma; g] \in \sigma(X, x_0, G)$, any element of the $(\varphi, \psi)_{\sigma}$ -equivalent class containing $[\beta; g_2]$ may be expressed in the form

$$[\alpha; g_1] = [\gamma; g][\beta; g_2](\varphi, \psi)_{\sigma}([\gamma; g]^{-1}).$$

From the above diagram, we can easily obtain

$$\begin{aligned} \theta_{\sigma}([\alpha; g_1]) &= \theta_{\sigma}([\gamma; g][\beta; g_2](\varphi, \psi)_{\sigma}([\gamma; g]^{-1})) \\ &= \theta_{\sigma}([\gamma; g]) + \theta_{\sigma}([\beta; g_2]) - \theta_{\sigma}(\varphi, \psi)_{\sigma}([\gamma; g]) \\ &= \theta_{\sigma}([\gamma; g]) + \theta_{\sigma}([\beta; g_2]) - (\varphi, \psi)_{\bar{\sigma}}\theta_{\sigma}([\gamma; g]) \\ &= \theta_{\sigma}([\beta; g_2]) + (1 - (\varphi, \psi)_{\bar{\sigma}})(\theta_{\sigma}([\gamma; g])). \end{aligned}$$

Thus there exists an element $[\gamma; g] \in \sigma(X, x_0, G)$ such that

$$\begin{aligned} \theta_{\sigma}([\alpha; g_1]) - \theta_{\sigma}([\beta; g_2]) &= \\ (1 - (\varphi, \psi)_{\bar{\sigma}})(\theta_{\sigma}([\gamma; g])) &\in (1 - (\varphi, \psi)_{\bar{\sigma}})(\bar{\sigma}(X, x_0, G)). \end{aligned}$$

Let $\eta_{\bar{\sigma}} : \bar{\sigma}(X, x_0, G) \rightarrow \text{Coker}(1 - (\varphi, \psi)_{\bar{\sigma}})$ be the natural projection. Now consider

$$\sigma(X, x_0, G) \xrightarrow{\theta_{\sigma}} \bar{\sigma}(X, x_0, G) \xrightarrow{\eta_{\bar{\sigma}}} \text{Coker}(1 - (\varphi, \psi)_{\bar{\sigma}}).$$

Since both θ_{σ} and $\eta_{\bar{\sigma}}$ are epimorphisms, $\eta_{\bar{\sigma}}\theta_{\sigma}$ is also an epimorphism. Moreover, the $\eta_{\bar{\sigma}}\theta_{\sigma}$ images of all element of a $(\varphi, \psi)_{\sigma}$ -equivalent class are the same element of $\text{Coker}(1 - (\varphi, \psi)_{\bar{\sigma}})$. This completes the proof of theorem. \square \square

COROLLARY 3.6. *Let $(\varphi, \psi) : (X, G) \rightarrow (X, G)$ be a self-map. If $\sigma(X, x_0, G)$ is abelian and G is abelian, then*

$$R(\varphi, \psi) = \# \text{Coker}(1 - (\varphi, \psi)_{\bar{\sigma}}).$$

Proof. If $\sigma(X, x_0, G)$ is abelian, then the natural homomorphism $\theta_{\sigma} : \sigma(X, x_0, G) \rightarrow \bar{\sigma}(X, x_0, G)$ is an isomorphism. From Definition 3.1, $[\alpha; g_1] \sim [\beta; g_2]$ if and only if there exists $[\gamma; g] \in \sigma(X, x_0, G)$ such that

$$\theta_{\sigma}([\alpha; g_1]) - \theta_{\sigma}([\beta; g_2]) = (1 - (\varphi, \psi)_{\bar{\sigma}})(\theta_{\sigma}([\gamma; g])),$$

In other words,

$$\eta_{\bar{\sigma}}\theta_{\sigma}([\alpha; g_1]) - \eta_{\bar{\sigma}}\theta_{\sigma}([\beta; g_2]) = 0.$$

This completes the proof of theorem. □ □

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